E-MANIP

- An innovative design for multiple applications!

- The E-Manip designed by the Guy Neyret company is based on the association of a ball screw spline and a ball screw. These both functions allow to generate separated or interpolated rotary and linear motions. The same device can be found on the Scara Robot pins.

- Unique in its design, the E-Manip meets the complex assemblies and test requirements.

- Flexibility
  - Multiple references (height & position)
  - Random speed
  - Spiral function, screwing
  - Force-stroke function with integrated control

Different versions for multiples functions & applications:

- Version « helicopter » for the transfer to substations.
- Version pick and place at various positions.
- Version extended arm.
- Version telescopic arm